

# Computing Greeks using multilevel path simulation

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# Introduction

- Financial assets evolution modelled as an SDE.
- Option's price is a functional of the underlying asset's price.
- Greeks: sensitivities of option's price to market parameters.
  - Underlying asset's price  $S_0$ , volatility  $\sigma$ , interest rate  $r$ ...
  - Measure exposure to different sources of risk.
- Estimation of option's price and Greeks with Monte Carlo.
- Computing Greeks is more challenging than pricing derivatives.
- Problems arise with discontinuous/nonsmooth payoffs.
- Multilevel path simulation to reduce computational complexity.

# Plan

- 1 Monte Carlo Greeks
  - Setting and finite differences
  - Pathwise Sensitivities
  - Likelihood Ratio Method
- 2 Multilevel Monte Carlo
  - Multilevel path simulation idea
  - MLMC Complexity
- 3 Multilevel Computation of Greeks
  - Applying the Multilevel idea to the computation of Greeks
  - Multilevel Pathwise Sensitivities
  - Multilevel Pathwise Sensitivities with Cond. Expectations
  - Multilevel Split Pathwise Sensitivities
  - Multilevel Vibrato Monte Carlo

# Monte Carlo Greeks

# Setting

Notation:

- Underlying asset  $S$ , value  $S_t$  at time  $t$
- Time interval  $[0, T]$  split in  $N$  timesteps of size  $h$ .
- Interest rate  $r$ , volatility  $\sigma$ .
- European option: payoff  $P(S_T)$ .

Evolution SDE for  $S$ :

- $dS(t) = a(S, t)dt + b(S, t)dW_t$
- Euler discretization:  $S_{n+1} = S_n + a(S_n, t_n) h + b(S_n, t_n) \Delta W_n$ .
- Milstein discretization:  $S_{n+1} = S_n + a(S_n, t_n) h + b(S_n, t_n) \Delta W_n + \frac{1}{2} b(S_n, t_n) \frac{db}{dS_n} \cdot (\Delta W_n^2 - h)$ .

## A naive method: finite differences

Pricing:

- The option's value for a certain parameter  $\theta$  is  $V(\theta) = \mathbb{E}(P(S_T))$ .
- Simulate paths for the underlying asset, get values of  $\hat{P}(S_T)$
- Compute MC estimate:  $\hat{V}(\theta)$ .

Finite differences:

- Take parameter  $\theta + \delta\theta$ , compute  $\hat{V}(\theta + \delta\theta)$
- $\frac{\partial V}{\partial \theta} \approx \frac{\hat{V}(\theta + \delta\theta) - \hat{V}(\theta)}{\delta\theta}$

Limitations:

- Requires two sets of calculations.
- Which  $\delta\theta$  ?
- Discretisation bias/Variance tradeoff.

# Pathwise Sensitivities

Principle:

- $\frac{\partial V}{\partial \theta} = \frac{\partial \mathbb{E}(P(S_T))}{\partial \theta} = \mathbb{E} \left( \frac{\partial P(S_T)}{\partial \theta} \right) = \mathbb{E} \left( \frac{\partial P}{\partial S} (S_T) \cdot \frac{\partial S_T}{\partial \theta} \right)$
- $\frac{\partial P}{\partial S}$  is a property of the payoff function.
- $\frac{\partial S_0}{\partial \theta}$  is known.
- $S_{n+1} = S_n + a(S_n, t_n) h + b(S_n, t_n) \Delta W_n$   
 $\Rightarrow \frac{\partial S_{n+1}}{\partial \theta} = \frac{\partial S_n}{\partial \theta} + \frac{\partial a(S_n, t_n)}{\partial \theta} h + \frac{\partial b(S_n, t_n)}{\partial \theta} \Delta W_n$

Limitations:

- $\frac{\partial P}{\partial S}$  must be defined almost everywhere.
- For the first line to be true,  $\frac{P(x+dx) - P(x)}{dx}$ , must be uniformly integrable.
- Practically,  $P$  Lipschitz is a sufficient condition.

# Likelihood Ratio Method

Principle:

- Let  $p(S)$  the p.d.f. of  $S_T$ .
- 

$$V = \mathbb{E}(P(S_T)) = \int P(S) p(S) dS$$
$$\Rightarrow \frac{\partial V}{\partial \theta} = \int P \frac{\partial p}{\partial \theta} dS = \int P \frac{\partial \log p}{\partial \theta} p dS = \mathbb{E}\left(P \frac{\partial \log p}{\partial \theta}\right)$$

Limitations:

- In most cases,  $p(S)$  is not known.
- Have to discretize  $[0, T]$  in time steps of size  $h$ .
- LRM not well suited for path simulations,  
 $V$  then explodes as  $\frac{1}{h}$ .



# Multilevel Monte Carlo

## Complexity Evaluation

We want a Monte Carlo option price with an accuracy  $\epsilon$ .

- 2 sources of error: discretisation ( $N$  steps), finite number of samples ( $M$ ).

Mean Square Error:  $(1/M) \mathbb{V}(\hat{P}) + (\mathbb{E}(\hat{P}) - \mathbb{E}(P))^2$ .

- 1st term  $\searrow$  with the number of paths  $M$ :  $\mathcal{O}(\frac{1}{M})$ .
- 2nd term  $\searrow$  with the number of steps  $N$ :  $\mathcal{O}(\frac{1}{N^2})$ .

We want to have these terms  $\mathcal{O}(\epsilon^2)$ .

- We set  $M = \mathcal{O}(\epsilon^{-2})$  and  $N = \mathcal{O}(\epsilon^{-1})$ .

Total complexity  $\mathcal{O}(NM) = \mathcal{O}(\epsilon^{-3})$  for option value - often worse for Greeks.

## Multilevel path simulation idea

We simulate paths at different levels of fineness:

- At level  $l$ ,  $l = 0 \dots L$ ,  $2^l$  timesteps of width  $h_l = T/2^l$ .
- Let  $\hat{P}_l$  be the payoff with level  $l$ 's discretisation.

We have  $\mathbb{E}(\hat{P}_L) = \mathbb{E}(\hat{P}_0) + \sum_{l=1}^L \mathbb{E}(\hat{P}_l - \hat{P}_{l-1})$ .

- With  $N_l$  samples, we estimate

$$\mathbb{E}(\hat{P}_l - \hat{P}_{l-1}) \simeq \hat{Y}_l = \frac{1}{N_l} \sum_{i=1}^{N_l} (\hat{P}_l^{(i)} - \hat{P}_{l-1}^{(i)})$$

- We estimate the different  $\hat{Y}_l$  independently.
- We reuse the leading brownian motion from  $\hat{P}_l$  in  $\hat{P}_{l-1}$ .

## Complexity Improvements

Variance of our combined estimator:

$$\bullet \mathbb{V}\left(\sum_{l=1}^L \hat{Y}_l\right) = \sum_{l=1}^L \left(\mathbb{V}(\hat{Y}_l)\right) = \sum_{l=1}^L \left(\frac{1}{N_l} \mathbb{V}(\hat{P}_l - \hat{P}_{l-1})\right)$$

Computational cost:

$$\bullet \text{Cost} \sum_{l=1}^L \left(N_l h_l^{-1}\right)$$

We target an accuracy  $\epsilon$ :

- Choose  $L$  to make the discretisation bias small enough.
- Take  $N_l \sim \kappa \sqrt{\mathbb{V}(\hat{P}_l - \hat{P}_{l-1})} h_l$  to minimise the variance at a fixed computational cost.
- Choose  $\kappa$  big enough to have a  $\mathcal{O}(\epsilon^2)$  variance overall.

# MLMC complexity theorem

## Theorem

$P$  is a functional of the solution of an SDE.  $\hat{P}_l$  is the approximation with a timestep  $h_l$ . If there are independent estimators  $\hat{Y}_l$  based on  $N_l$  samples of cost  $C_l$  and constants  $\alpha \geq \frac{1}{2}, \beta, c_1, c_2, c_3$  such that

- 1  $\mathbb{E}(\hat{Y}_0) = \mathbb{E}(\hat{P}_0), \quad \forall l \geq 1 \quad \mathbb{E}(\hat{Y}_l) = \mathbb{E}(\hat{P}_l - \hat{P}_{l-1})$
- 2  $|\mathbb{E}(\hat{P}_l - P)| \leq c_1 h_l^\alpha$
- 3  $\mathbb{V}(\hat{Y}_l) \leq c_2 N_l^{-1} h_l^\beta$
- 4  $C_l \leq c_3 N_l h_l^{-1}$

# MLMC complexity theorem

## Theorem

Then there exists a constant  $c_4$  such that for any  $\epsilon < e^{-1}$  there are values of  $L$  and  $N_l$  for which the estimator  $\hat{Y} = \sum_{l=0}^L \hat{Y}_l$

- 1 Has an MSE  $\mathbb{E} \left[ \left( \hat{Y} - \mathbb{E}(P) \right)^2 \right] < \epsilon^2$
- 2 With a complexity

$$C \leq \begin{cases} c_4 \epsilon^{-2} & \text{if } \beta > 1 \\ c_4 \epsilon^{-2} (\log \epsilon)^2 & \text{if } \beta = 1 \\ c_4 \epsilon^{-2 - (1-\beta)/\alpha} & \text{if } 0 < \beta < 1 \end{cases}$$

## Comments on the complexity theorem

The parameter  $\alpha$  is known thanks to literature on weak convergence of discretisation schemes.

- Euler and Milstein discretisation:  $\alpha = 1$ , even with discontinuous payoffs (Bally and Talay, 1995).

The parameter  $\beta$  is related to strong convergence, it determines the efficiency of the multilevel approach.

- For a Lipschitz payoff, Euler:  $\beta = 1$ , Milstein:  $\beta = 2$ ,
- Not as good for discontinuous payoffs.
- Generally we do not know  $\beta$  *a priori*.

We must create estimators  $\hat{Y}_l$  with  $\beta$  as large as possible.

- Pathwise sensitivities reduce the smoothness by one order.
- Multilevel Greeks of nonsmooth payoffs are challenging.

# Multilevel Computation of Greeks



## Multilevel Greeks estimators

We can write

$$\frac{\partial V}{\partial \theta} = \frac{\partial \mathbb{E}(P)}{\partial \theta} \approx \frac{\partial \mathbb{E}(\hat{P}_L)}{\partial \theta} = \frac{\partial \mathbb{E}(\hat{P}_0)}{\partial \theta} + \sum_{l=1}^L \frac{\partial \mathbb{E}(\hat{P}_l - \hat{P}_{l-1})}{\partial \theta}$$

We estimate this value with

$$\begin{cases} \hat{Y}_0 = \frac{1}{N_0} \sum_{i=1}^M \frac{\partial \hat{P}_0^{(i)}}{\partial \theta} \\ \hat{Y}_l = (1/N_l) \sum_{i=1}^{N_l} \left( \frac{\partial \hat{P}_l^{(i)}}{\partial \theta} - \frac{\partial \hat{P}_{l-1}^{(i)}}{\partial \theta} \right), \quad 1 \leq l \leq L \end{cases}$$

We compute  $\frac{d\hat{P}_0^{(i)}}{d\theta}$ ,  $\frac{d\hat{P}_{l-1}^{(i)}}{d\theta}$ ,  $\frac{d\hat{P}_l^{(i)}}{d\theta}$  as normal MC Greeks with LRM, PwS...

## Numerical Experiments

We consider one underlying asset  $S$ :

- Black & Scholes  $dS_t = r S_t dt + \sigma S_t dW_t$

- Milstein discretization:

$$S_{n+1} = S_n \cdot \left( 1 + r h + \sigma \Delta W_n + \frac{\sigma^2}{2} (\Delta W_n^2 - h) \right) := S_n \cdot D_n$$

We consider European options, illustration with:

- Call:  $P(S) = \max(S_T - K, 0)$  (Lipschitz).
- Digital call:  $P(S) = \mathbf{1}_{S_T > K}$  (Discontinuous).

We illustrate our methods with two sensitivities:

- $\Delta$ : sensitivity to  $S_0$ .
- $\nu$ : sensitivity to  $\sigma$ .

# Multilevel Pathwise Sensitivities

Conditions:

- $P$  Lipschitz.
- Only works for the European call.

Implementation (call):

- $\hat{Y}_l = \frac{1}{N_l} \sum \left[ \left( \frac{\partial S}{\partial \theta} \frac{\partial P}{\partial S} \right)^{(l)} - \left( \frac{\partial S}{\partial \theta} \frac{\partial P}{\partial S} \right)^{(l-1)} \right]$
- $\frac{\partial S}{\partial \theta}$  via recurrence:
  - $\frac{\partial S_{n+1}}{\partial S_0} = \frac{\partial S_n}{\partial S_0} \cdot D_n$
  - $\frac{\partial S_{n+1}}{\partial \sigma} = \frac{\partial S_n}{\partial \sigma} \cdot D_n + S_n(\Delta W_n + \sigma(\Delta W_n^2 - h))$
- Sum pairs of fine brownian increments to get coarse increments.
  - Saves the cost of generating new increments.
  - The coarse and rough paths are close  $\Rightarrow \mathbb{V}(\hat{Y}_l)$  is smaller.

## Multilevel PwS Results

Numerical estimate of  $\beta$  + theorem  $\Rightarrow$  Estimated complexity.

European Call:

- Value's estimator:  $\beta \approx 2.0 \Rightarrow$  Complexity  $\mathcal{O}(\epsilon^{-2})$ .
- Delta's estimator:  $\beta \approx 0.8 \Rightarrow$  Complexity  $\mathcal{O}(\epsilon^{-2.2})$ .
- Vega's estimator:  $\beta \approx 1 \Rightarrow$  Complexity  $\mathcal{O}(\epsilon^{-2}(\log \epsilon)^2)$ .

## PwS and Conditional Expectations

Reasons:

- Extending the PwS to discontinuous payoffs.
- Payoff smoothing unsatisfactory: tradeoff bias/variance.
- Improving Greeks' convergence rates with nonsmooth payoffs.

Conditional expectation technique:

- $\hat{S}_N(W, Z) = \hat{S}_{N-1}(1 + r h) + \sigma \hat{S}_{N-1} \sqrt{h} Z := \mu_W + \sigma_W Z$
- $p(\hat{S}_N|W) = \frac{1}{\sigma_W \sqrt{2\pi}} \exp\left(-\frac{(\hat{S}_N - \mu_W)^2}{2\sigma_W^2}\right)$
- Tower property :  $\mathbb{E}(P(\hat{S}_N)) = \mathbb{E}_W \left[ \mathbb{E}_Z(P(\hat{S}_N)|W) \right]$ .
- $\mathbb{E}(P(\hat{S}_N)|W) = \Phi\left(\frac{\mu_W - K}{\sigma_W}\right)$  for the digital call.
- Apply the Multilevel PwS method to this differentiable function.

## Multilevel PwS Cond Exp results

### Implementation

- Use final step's first half to reduce variance.
- $\Delta W_{N-1}^{(c)} = \Delta W_{2N-2}^{(f)} + \Delta W_{2N-1}^{(f)}$
- Tower prop:  $\mathbb{E} \left[ P(\hat{S}_N) | W \right] = \mathbb{E} \left[ \mathbb{E} (P(\hat{S}_N) | W, \Delta W_{2N-2}^{(f)}) | W \right]$ .
- $\mathbb{E} (P(\hat{S}_N) | W, dW_{2N-2}^{(f)}) = \Phi \left( \frac{\mu_W + \sigma_W / \sqrt{h_f} \cdot \Delta W_{2N-2}^{(f)} - K}{\sigma_W} \right)$ .

### Digital Call:

- Value's estimator:  $\beta = 1.5 \Rightarrow$  Complexity  $\mathcal{O}(\epsilon^{-2})$ .
- Delta's estimator:  $\beta = 0.5 \Rightarrow$  Complexity  $\mathcal{O}(\epsilon^{-2.5})$ .
- Vega's estimator:  $\beta = 0.6 \Rightarrow$  Complexity  $\mathcal{O}(\epsilon^{-2.4})$ .

### European Call:

- Value's estimator:  $\beta = 2 \Rightarrow$  Complexity  $\mathcal{O}(\epsilon^{-2})$ .
- Delta's estimator:  $\beta = 1.5 \Rightarrow$  Complexity  $\mathcal{O}(\epsilon^{-2})$ .
- Vega's estimator:  $\beta = 2 \Rightarrow$  Complexity  $\mathcal{O}(\epsilon^{-2})$ .

## Split Pathwise Sensitivities

Limitations of conditional expectations:

- Need an analytical expression for  $\mathbb{E}(P(\hat{S}_N)|\hat{S}_{N-1})$  and its derivative.

Principle:

- Numerical approximation of a conditional expectation.
- Split each path, take  $d$  samples for the final increment.
- $\mathbb{E}(P(\hat{S}_N)|\hat{S}_{N-1}) \approx \frac{1}{d} \sum_{m=1}^d P(\hat{S}_{N-1}^{(m)} \cdot D_{N-1}^{(m)})$ .
- $\frac{\partial \mathbb{E}(P(\hat{S}_N)|\hat{S}_{N-1})}{\partial \hat{S}_{N-1}} \approx \frac{1}{d} \sum_{m=1}^d \left( \frac{\partial P}{\partial \hat{S}_N} \frac{\partial \hat{S}_N}{\partial \hat{S}_{N-1}} \right)(m)$ .
- Use these expressions as before in Multilevel PwS with Conditional Expectations.

Warning:

- Conditions apply for Greeks.

## Multilevel Split PwS results

European Call,  $d = 1$  (Same as PwS) :

- Value's estimator:  $\beta \approx 2.0 \Rightarrow$  Complexity  $\mathcal{O}(\epsilon^{-2})$  .
- Delta's estimator:  $\beta \approx 0.9 \Rightarrow$  Complexity  $\mathcal{O}(\epsilon^{-2.1})$ .
- Vega's estimator:  $\beta \approx 1.3 \Rightarrow$  Complexity  $\mathcal{O}(\epsilon^{-2})$ .

European Call,  $d = 20$ :

- Value's estimator:  $\beta \approx 2.0 \Rightarrow$  Complexity  $\mathcal{O}(\epsilon^{-2})$  .
- Delta's estimator:  $\beta \approx 1.1 \Rightarrow$  Complexity  $\mathcal{O}(\epsilon^{-2})$ .
- Vega's estimator:  $\beta \approx 1.8 \Rightarrow$  Complexity  $\mathcal{O}(\epsilon^{-2})$ .

European Call,  $d = 500$  (Similar to PwS with Cond. Expectations):

- Value's estimator:  $\beta \approx 2.0 \Rightarrow$  Complexity  $\mathcal{O}(\epsilon^{-2})$  .
- Delta's estimator:  $\beta \approx 1.5 \Rightarrow$  Complexity  $\mathcal{O}(\epsilon^{-2})$ .
- Vega's estimator:  $\beta \approx 2.0 \Rightarrow$  Complexity  $\mathcal{O}(\epsilon^{-2})$ .



# Vibrato Monte Carlo

## Goal and Principle:

- Approximate Conditional Expectations for discontinuous  $P$ .
- $\hat{S}_N = \mu_W + \sigma_W Z$ .
- Use PwS on  $W$  and LRM on last step  $Z$ .

## Principle

- $V = \mathbb{E}_W \left[ \mathbb{E}_Z(P(\hat{S}_N) | W) \right]$
- $\frac{\partial V}{\partial \theta} = \mathbb{E}_W \left[ \frac{\partial}{\partial \theta} \mathbb{E}_Z(P(\hat{S}_N) | W) \right] = \mathbb{E}_W \left[ \mathbb{E}_Z(P(\hat{S}_N) \frac{\partial(\log p_S)}{\partial \theta} | W) \right]$
- $\frac{\partial}{\partial \theta}(\log p_S) = \frac{\partial}{\partial \mu_W}(\log p_S) \cdot \frac{\partial \mu_W}{\partial \theta} + \frac{\partial}{\partial \sigma_W}(\log p_S) \cdot \frac{\partial \sigma_W}{\partial \theta}$ 
  - $\frac{\partial}{\partial \mu_W}(\log p_S), \frac{\partial}{\partial \sigma_W}(\log p_S)$  simple functions of  $Z$ .
  - $\frac{\partial \mu_W}{\partial \theta}, \frac{\partial \sigma_W}{\partial \theta}$  known by PwS.

# Vibrato Monte Carlo - Multilevel

## Multilevel Implementation:

- Treatment similar to Split PwS.
- Final step at coarse level:

- $\Delta W_{N-1}^{(c)} = \Delta W_{2N-2}^{(f)} + \Delta W_{2N-1}^{(f)}$

- $V = \mathbb{E}_W \left[ \mathbb{E} \left[ P(\hat{S}_N) | W \right] \right]$   
 $= \mathbb{E}_W \left[ \mathbb{E} \left[ \mathbb{E}(P(\hat{S}_N) | W, \Delta W_{2N-2}^{(f)}) | W \right] \right].$

- Apply LRM to  $\frac{\partial}{\partial \theta} \mathbb{E}(P(\hat{S}_N) | W, \Delta W_{2N-2}^{(f)})$ .

- $\frac{\partial V}{\partial \theta} =$   
 $\mathbb{E}_W \left[ \mathbb{E}_{\Delta W_{2N-2}^{(f)}} \left[ \mathbb{E}_{\Delta W_{2N-1}^{(f)}} \left( P(\hat{S}_N) \frac{\partial(\log ps)}{\partial \theta} | W, \Delta W_{2N-2}^{(f)} \right) | W \right] \right]$

## Vibrato Monte Carlo results

European Call,  $d = 100$ :

- Value's estimator:  $\beta \approx 2.0 \Rightarrow$  Complexity  $\mathcal{O}(\epsilon^{-2})$ .
- Delta's estimator:  $\beta \approx 1.5 \Rightarrow$  Complexity  $\mathcal{O}(\epsilon^{-2})$ .
- Vega's estimator:  $\beta \approx 2.0 \Rightarrow$  Complexity  $\mathcal{O}(\epsilon^{-2})$ .

Digital Call,  $d = 100$ :

- Value's estimator:  $\beta \approx 1.2 \Rightarrow$  Complexity  $\mathcal{O}(\epsilon^{-2})$ .
- Delta's estimator:  $\beta \approx 0.3 \Rightarrow$  Complexity  $\mathcal{O}(\epsilon^{-2.7})$ .
- Vega's estimator:  $\beta \approx 0.5 \Rightarrow$  Complexity  $\mathcal{O}(\epsilon^{-2.5})$ .

Remarks:

- $d \gg 1$  is important to get good approximates of good approximates of Cond. Exp.
- $d = 500 \dots \beta$  similar to Cond. Exp. (1.5, 0.5, 0.6)

# Conclusion

## Final Words

MLMC provides computational savings for the computation of Greeks:

- Benefits dependent on  $\beta$ , convergence rate of  $\mathbb{V}(\hat{Y}_T)$ .
- Discontinuous/nonsmooth payoffs are challenging:
  - Special treatment (Cond. Exp., Vibrato).
  - Smaller  $\beta$ .

Unexpected result:

- $\nu$  converges slightly faster than  $\Delta$ .
- Consistent feature across all simulations.

Research will now focus on a rigorous numerical analysis of MLMC for Greeks.